# MATHEMATICAL MODEL FOR LINEAR ANALYSIS OF THE STABILITY OF A SYSTEM DURING UNIDIRECTIONAL SOLIDIFICATION WITH BUOYANCY AND SMALL SEGREGATION COEFFICIENT

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# ABSTRACT

In this study, the stability of a coupled morphological-convective system during unidirectional solidification with buoyancy is discussed for small segregation coefficient as well as a small wave number. The effects of the constraints like rotation, permeability and quadratic density profile are investigated by considering linear theory. Expressions for the growth rate, critical conditions and solutions corresponding to different order of approximations are determined by using power-series expansion technique with boundary conditions.

Keywords: Linear Analysis, Buoyancy, Small Segregation Coefficient, Small Wave Number.

# I. INTRODUCTION

Three models like rotation, permeability and quadratic density profile are investigated using linear theory in detail. Expressions for the growth rate, critical conditions and solutions corresponding to different order of approximations are determined. The physical configuration (Figure 2.1) consists of a binary-alloy melt which is directionally solidified at constant speed V.



Under the assumptions and approximations [1], [6] and [7], the heat generated at the solidifying front can be neglected and accordingly, it can be presumed that the interfacial perturbations do not give rise to disturbances of the temperature field. Therefore, the temperature field can be considered to be fixed as:

$$\mathsf{T} = \mathsf{T}_0 + \mathsf{G}\,\mathsf{z} \tag{9.1.1}$$

Where, T0 is the reference temperature of the undisturbed planar interface; G is the imposed temperature gradient and z = 0 is the mean position of the interface.

# **II. MATHEMATICAL FORMULATION**

In this study, the mathematical formulation has been constituted in a frame of reference moving at the velocity V (the crystal growth rate) as given in the following equations [1], [3] and [7]: The conservation of momentum:

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \nabla \frac{\partial \mathbf{u}}{\partial z} = -\frac{\nabla p}{\rho_0} + v \nabla^2 \mathbf{u} + \frac{\delta \rho}{\rho_0} g \mathbf{k}^{\wedge}$$

(9.1.2)

The conservation of solute in the melt:

$$\frac{\partial \mathbf{c}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{c} - \mathbf{V} \frac{\partial \mathbf{c}}{\partial z} = \mathbf{D} \nabla^2 \mathbf{c}$$
(9.1.3)

The conservation of mass:

$$\nabla$$
. u = 0

Where, **U** is the fluid velocity, p is the reduced fluid pressure, c is the mass concentration of the solute in the

fluid,  $P_0$  is the reference density and V is the kinematic viscosity of the fluid. The diffusion of the solute in the solid phase is also neglected. The quadratic density profile is given by:

$$\frac{\delta\rho}{\rho_0} = \beta (\boldsymbol{c} - \boldsymbol{C}_f)^2 \tag{9.1.5}$$

Where,  $\delta \rho$  is the change in the density;  $\beta(>0)$  is the solutal coefficient of expansion;  $C_f$  is the concentration of the solute in the fluid at the interface.

#### 2.1 Boundary Conditions

Under the assumption, if the density changes upon solidification is negligible, the no-slip condition and the mass balance condition are: u=0 (9.1.6) The mean position of the interface is taken as z = h (x, y, t) and the conservation of solute at the interface: c(1-k)(V+h t) = -D(cz - cxhx - cyhy), where, the subscript denotes the derivative. (9.1.7) The condition of thermodynamic equilibrium:

$$T = mc + TM \begin{bmatrix} 1 + L & K \end{bmatrix}, \quad T_0 + Gh = mc + T_M \begin{bmatrix} 1 + \frac{Y}{L}K \end{bmatrix} \quad \text{from (9.1.1)}$$
(9.1.8)

Where, m is the liquidus (figure 2.2) slope, TM is the melting point of the pure substance,  $\gamma$  is the surface free energy, L is the latent heat and K is twice the mean curvature:

$$\mathbf{K} = \left[ \mathbf{h}_{xx} \left( 1 + \mathbf{h}_{y}^{2} \right) - 2\mathbf{h}_{x} \mathbf{h}_{y} \mathbf{h}_{xy} + \mathbf{h}_{yy} \left( 1 + \mathbf{h}_{x}^{2} \right) \right] \cdot \left( 1 + \mathbf{h}_{x}^{2} + \mathbf{h}_{y}^{2} \right)^{\frac{3}{2}}$$
(9.1.9)

Far away from the interface, the velocity field is considered to be bounded and the solute concentration is equal to  $C_s$ , which is the concentration of the solute in the solid phase.

#### 2.2 Basic State Solution

The study-state solution constitutes:

International Journal of Advanced Technology in Engineering and Science www.ijates.com Volume No.02, Issue No. 10, October 2014 ISSN (online): 2348-7550 (i) A planar interface  $h \equiv 0$  (9.1.10), (ii) Zero melt velocity  $(\mathbf{u} \equiv 0)$  (9.1.11)  $T = \frac{mC_s}{k} + T_M.....(9.1.12)$ (iii) The reference temperature of the planar interface:  $G_{c} = \frac{(k-1)C_{s}V}{k}$ (iv) The solute gradient at the interface: (9.1.13) $\boldsymbol{c} = \frac{\boldsymbol{C}_s}{\boldsymbol{k}} + \left(\frac{\boldsymbol{G}_c \boldsymbol{D}}{\boldsymbol{V}}\right) \left| 1 - \boldsymbol{e}^{\left(-\boldsymbol{V} \boldsymbol{Z}_{\boldsymbol{D}}\right)} \right|$ (v) The concentration field: (9.1.14) $\delta = \frac{D}{V}$  is the concentration boundary-layer thickness Where, (9.1.15)The governing equations (9.1.2) to (9.1.4) are made dimensionless by using the following scales [2] and [4]: Length:  $\mathbf{x} = \delta \mathbf{x}', \ \mathbf{y} = \delta \mathbf{y}', \ \mathbf{z} = \delta \mathbf{z}', \ \mathbf{h} = \delta \mathbf{h}', \ \text{Velocity:} \ \mathbf{u} = \mathbf{V} \mathbf{u}', \ \mathbf{v} = \mathbf{V} \mathbf{v}', \ \mathbf{w} = \mathbf{V} \mathbf{w}'$ Pressure:  $P = \frac{\mu V^2}{D} p'$ ; Time:  $t = \frac{D}{V^2} t'$ ; Concentration:  $c - \frac{C_s}{k} = \left(\frac{G_c D}{V}\right) c'$ (9.1.16) The resulting dimensionless equations are:  $S^{-1} \left| \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \frac{\partial \mathbf{u}}{\partial z} \right| = -\nabla p + \nabla^2 \mathbf{u} - RC^* c^2 \mathbf{k}$ (9.1.17) $\frac{\partial c}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{c} - \frac{\partial c}{\partial \mathbf{z}} = \nabla^2 \mathbf{c}$ (9.1.18);  $\nabla \cdot \mathbf{u} = 0$  (9.1.19)  $S = \frac{v}{D}$ : Schmidt number;  $M = \frac{mG_c}{G}$ : the Morphological parameter;  $R = -\frac{g\beta G_{e}}{vD} \left(\frac{D}{V}\right)^{4} = \frac{(1-k)C_{s}g\beta}{kvD} \left(\frac{D}{V}\right)^{3}$  the solute Rayleigh number; (9.1.20) $\Gamma = \frac{T_{M}\gamma}{LmG_{c}} \left(\frac{V}{D}\right)^{2}$ : surface free energy parameter;  $\mathbf{C}^* = \left(\frac{\pounds - \mathbf{1}}{\pounds}\right) \mathbf{C}_s$ : Segregation ratio; z = h(x, y, t) in the The interface dimensionless form are (9.1.21)given by: u=0 $[c(k-1)+1](1+h_{t})=c_{z}-h_{x}c_{x}-h_{y}c_{y}$ (9.1.22) $\boldsymbol{c} - \boldsymbol{M}^{-1} \boldsymbol{h} + \Gamma \left[ \boldsymbol{h}_{xx} (1 + \boldsymbol{h}_{y}^{2}) - 2\boldsymbol{h}_{x} \boldsymbol{h}_{y} \boldsymbol{h}_{xy} + \boldsymbol{h}_{yy} (1 + \boldsymbol{h}_{x}^{2}) \right] \left[ (1 + \boldsymbol{h}_{x}^{2} + \boldsymbol{h}_{y}^{2}) \right]^{-\frac{3}{2}} = 0$ (9.1.23)From (9.1.19) and (9.1.21), we have D w = 0 at the interface (9.1.23a) Far away from the interface (i.e. as  $Z \rightarrow \infty$ ) the conditions are:  $|\mathbf{u}| < \infty$  $c = 1 \dots (9.1.24)$ Thus, the dimensionless basic state solution:

$$\vec{u} = \vec{v} = \vec{w} = 0_{\dots} (9.1.25); \quad \vec{h} = 0_{(9.1.26)}; \quad \vec{c} = 1 - e^{-z} (9.1.27)$$

Equation (9.1.17) in the component form:

$$\mathbf{S}^{-1} \left[ \frac{\partial \mathbf{u}}{\partial \mathbf{t}} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \frac{\partial \mathbf{u}}{\partial \mathbf{z}} \right] = -\frac{\partial \mathbf{p}}{\partial \mathbf{x}} + \nabla^2 \mathbf{u}$$
(9.1.28)

$$\mathbf{S}^{-1} \left[ \frac{\partial \mathbf{v}}{\partial \mathbf{t}} + (\mathbf{U} \cdot \nabla) \mathbf{v} - \frac{\partial \mathbf{v}}{\partial \mathbf{z}} \right] = -\frac{\partial \mathbf{p}}{\partial \mathbf{y}} + \nabla^2 \mathbf{v}$$
(9.1.29)

$$\mathbf{S}^{-1}\left[\frac{\partial \mathbf{w}}{\partial \mathbf{t}} + (\mathbf{U} \cdot \nabla)\mathbf{w} - \frac{\partial \mathbf{w}}{\partial z}\right] = -\frac{\partial \mathbf{p}}{\partial z} + \nabla^2 \mathbf{w} - \mathbf{R}\mathbf{C}^* \mathbf{c}^2$$
(9.1.30)

The pressure, in (9.1.28) - (9.1.30), is eliminated by applying the operator curl twice on (9.1.17). The resulting equation in the vertical component of velocity is given by:

$$S^{-1} \left[ \frac{\partial}{\partial t} \nabla^2 \mathbf{w} + \nabla^2 (\mathbf{u} \cdot \nabla) \mathbf{w} - \frac{\partial}{\partial z} \nabla^2 \mathbf{w} \right] = \nabla^4 \mathbf{w} - \mathbf{RC}^* \nabla_1^2 \mathbf{c}^2$$
(9.1.31)
Where, 
$$\nabla_1^2 \equiv \frac{\partial^2}{\partial \mathbf{x}^2} + \frac{\partial^2}{\partial \mathbf{y}^2}$$
is the two - dimensional Laplacian operator

## **III. LINEAR STABILITY ANALYSIS**

The stability of the melt for infinitesimal perturbations is discussed. Widely used and accepted method is employed in the study [7]. The Leading-order solutions as well as corrections to the leading-order solutions are computed by considering higher order approximations. To introduce disturbances to the basic state as follows:  $(u,v,w)=(0,0,0)+\varepsilon(U,V,W)$ (0.1.22)

$$h=0+\epsilon H$$
(9.1.32)
$$c=1-e^{-z}+\epsilon C$$
(9.1.34)

Substituting the above equations such as (9.1.32), (9.1.33), (9.1.34) with (9.1.14), (9.1.31), (9.1.21) to (9.1.25) and then linearising with respect to  $\varepsilon$ , we get the set of differential equations in terms of  $\varepsilon$ . The normal modes for each of the dependent variable as  $f(x,y,z,t) = F(z)g(x,y)e^{\sigma t}$  (9.1.35)

Where, 
$$g(x,y)_{\text{satisfies:}} g_{xx} + g_{yy} = -a^2 g$$
 (9.1.36)

And the growth rate  $\sigma$  determines the stability of the marginal state. In (9.1.36), 'a' is the horizontal wave number. By equating the coefficient of  $\varepsilon$  from the resulting equation, to obtain the system of equations as follows:

$$S^{-1} \left[ \sigma \left( \frac{d^{2}}{dz^{2}} - a^{2} \right) W - \frac{d}{dz} \left( \frac{d^{2}}{dz^{2}} - a^{2} \right) W \right] = \left( \frac{d^{2}}{dz^{2}} - a^{2} \right)^{2} W + RC^{*} a^{2} \left( 2C - 2Ce^{-Z} \right)$$
  

$$\left( \frac{d^{2}}{dz^{2}} - a^{2} \right) \left[ \frac{d^{2}}{dz^{2}} + S^{-1} \frac{d}{dz} - a^{2} - S^{-1} \sigma \right] W = -2RC^{*} a^{2} \left( 1 - e^{-Z} \right) C$$
(9.1.37)

$$\left[\frac{d^2}{dz^2} + S^{-1}\frac{d}{dz} - a^2 - \sigma\right]C = We^{-Z}$$
(9.1.38)

The associated boundary conditions at the undisturbed interfacial position:

$$z = 0, \quad W = \frac{dW}{dz} = 0$$
 (9.1.39)

$$\frac{dC}{dz} + (1-k)C - (\sigma+k)H = 0$$
(9.1.40)

$$(M^{-1} - 1)H - C + \Gamma a^2 H = 0 \tag{9.1.39}$$

Far away from the interface as  $z \rightarrow \infty$ ,  $|W| < \infty$ .  $C \rightarrow 0$ 

Perturbation i.e. H, where

By solving (9.1.40), obtained the linearized thermodynamic equilibrium equation for the interfacial

$$H = \frac{C}{\left[a^{2}\Gamma - 1 + M^{-1}\right]}$$
(9.1.42)

From (9.1.42), it is clear that if  $M \rightarrow 0$ , then H is forced to tend to be zero and this corresponds to the unperturbation state. This result is very much consistent with (9.1.20). In other words, there will be no morphological instability if the under cooling is set equal to be zero. Further, the substitution of (9.1.42) with (9.1.40) yields the equation of the mass conservation of solute at the interface:

$$\frac{dC}{dz} + (1-k)C - \frac{(\sigma+k)C}{[a^2\Gamma - 1 + M^{-1}]} = 0$$
(9.1.42)

Where, due to an interfacial-shape change, the third term represents the perturbation in the concentration field. From (9.1.42), it follows that near the critical value for the onset of convection for which  $M \rightarrow I$ , the third term will be proportional to  $\sqrt{a^2}$ . It is clear that, if the wave number is sufficiently small, then this term would dCdefinitely dominate the diffusion term dz and this is a singular perturbation. Then from Physics, it follows  $\frac{D}{V}\frac{2\pi}{a}$ that, the dimensional wavelength or the characteristic cell size of an interfacial perturbation is (9.1.43)From (9.1.43), it is implied that decrease in 'a' leads to increase in the wavelength. In other words, the cell size exceeds the diffusional width for very small values of 'a'. Thus, the cell gets elongated at the onset of instability (M=1). In the further analysis, the whole problem is rescaled for k << 1 under the assumption that 'a' is also very smaller

than 1. Thus, to introduce:  $\hat{k} = a^2 \tilde{k}$  and  $\sigma = a^2 \tilde{\sigma}$ (9.1.44)

The governing system of equations under this new scaling becomes:

$$\left(\frac{d^2}{dz^2} - a^2\right)\left[\frac{d^2}{dz^2} + S^{-1}\frac{d}{dz} - a^2(1 + S^{-1}\widetilde{\sigma})\right]W = -2RC^2a^2(1 - e^{-Z})C$$
(9.1.45)

$$\left[\frac{\mathrm{d}}{\mathrm{d}z^2} + \frac{\mathrm{d}}{\mathrm{d}z} - \mathrm{a}^2(1+\tilde{\sigma})\right]\mathrm{C} = \mathrm{W}\mathrm{e}^{-\mathrm{Z}}$$
(9.1.46)

$$=\frac{\mathrm{dW}}{\mathrm{d}\,\mathrm{z}}=0\tag{9.1.47}$$

Together with the conditions at z=0:

$$\frac{dC}{dz} + \left(1 - a^2 \widetilde{k}\right)C - \frac{a^2 \left(\widetilde{\sigma} + \widetilde{k}\right)C}{\left(M^{-1} - 1 + a^2\Gamma\right)} = 0$$
(9.1.48)

And far away from the interface as  $z{\rightarrow}\infty,$   $|W|{<}\infty,$   $C{\rightarrow}0$  . (9.1.49)

(9.1.41)

# **3.1 The Solution Procedure**

To introduce power-series expansion for all the dependent variables of the problem under consideration as follows:

$$W = W_0 + a^2 W_1 + \dots + C = C_0 + a^2 C_1 + \dots + C =$$

By substituting power-series expansion of (9.1.50) with (9.1.45) to (9.1.49) and also equating the like powers

of  $a^2$  to get a set of differential equations corresponding to different order of approximations, the leading order will be:

$$\begin{pmatrix} \frac{d^{2}}{dz^{2}} \begin{pmatrix} \frac{d}{dz} + S^{-1} \end{pmatrix} W_{0} = 0$$
(9.1.51)  

$$\frac{d}{dz} \begin{pmatrix} \frac{d}{dz} + 1 \end{pmatrix} C_{0} = W_{0} e^{-Z}$$
(9.1.52)  
With  $W_{0} = DW_{0} = 0_{at \ z=0}; |W_{0}| < \infty_{as \ z \to \infty}; (D+1)C_{0} = 0_{at \ z=0}; C_{0} \to 0_{as \ z \to \infty}$ (9.1.58)  
The corresponding solutions are:  

$$W_{0} = 0$$
(9.1.54)  

$$C_{0} = Ae^{-Z}, \text{ where A is an arbitrary constant}$$
(9.1.55)  
The equations at  $O(a^{2})$  are,  

$$\begin{pmatrix} \frac{d^{2}}{dz^{2}} \end{pmatrix} \begin{pmatrix} \frac{d}{dz} + S^{-1} \end{pmatrix} W_{i} = -2RCA(e^{-zZ} - e^{-Z})$$
(9.1.56)  

$$\frac{d}{dz} \begin{pmatrix} \frac{d}{dz} + 1 \end{pmatrix} C_{i} - (1+\vec{\sigma})C_{0} = We^{-Z}$$
(9.1.57)  
With  $W_{i} = \frac{dW_{i}}{dz} = 0$ (9.1.57)  

$$W_{i} = \frac{dW_{i}}{dz} = 0$$
(9.1.58)  
The corresponding solutions are:  

$$W_{i} = -A_{1i} + A_{1i}e^{-Z_{i}} + A_{1i}e^{-Z_{i}} - A_{1i}e^{-Z}$$
(9.1.59)  

$$W_{i} = -A_{1i} + A_{2i}e^{-Z_{i}} + A_{ie}e^{-Z_{i}} - A_{ie}e^{-Z}$$
(9.1.59)  

$$W_{here}, A_{11} = \frac{7}{4}ARCS, A_{12} = \frac{2A_{1i}(7S-3)S}{7(S-1)(2S-1)}, A_{13} = \frac{A_{1i}}{7(2S-1)}, A_{14} = \frac{8}{7}\frac{A_{1i}}{(S-1)}$$
(9.1.60)  

$$W_{here}, A_{15} = RC^{*}S$$
(9.1.61)

Now substituting and simplifying the expression for  $C_1$  into the last equation of (9.1.58), we find the expression for the growth rate  $\sigma$ :

$$\sigma = \left[\frac{a^{2}(1-M^{-1})-a^{4}\Gamma}{(M^{-1}+a^{2}\Gamma)}\right] \left[1-\left\{\frac{5 R C^{*}}{6(1+S^{-1})}\right\}\right] - k$$
(9.1.62)

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Although the general form of  $\sigma$  corresponding to linear and quadratic density profiles is same and also the influence of quadratic profile is clearly seen in the second part of the first term, in the absence of gravity (i.e. R=0) in the limit of M=1 and  $a^2$  being very small then, the equation (9.1.62) reduces to:  $\sigma = (1 - M^{-1})a^2 - a^4\Gamma - k$ (9.1.63)

This result is identical to that of linear density profile (since R=0) and also, this expression is identical to that of [5] and [7]. From (9.1.63), we compute the critical values of R and by setting  $\sigma = 0$ . Thus,

$$R = \frac{6(1+S^{-1})}{5C^{*}} \left[ 1 - k \left( \frac{M^{-1} + a^{2}\Gamma}{(1-M^{-1})a^{2} - a^{4}\Gamma} \right) \right]$$
(9.1.64)  
and the condition  $\frac{dR}{da^{2}} = 0$  for optimality yields:  
$$R_{c}C^{*} = \left\{ \frac{6(1+S^{-1})}{5} \right\} \left[ 1 - k\Gamma \left( 1 - M^{-\frac{1}{2}} \right)^{2} \right]$$
(9.1.65)  
Where,  $a_{c}^{2}$  satisfies the equation:  $\Gamma^{2}(a^{2})^{2} + 2M^{-1}\Gamma a^{2} - M^{-1}(1-M^{-1}) = 0$ (9.1.66)  
Solving (9.1.66), we obtain  $a_{c}^{2} = M^{-1}\Gamma^{-1}(M^{\frac{1}{2}} - 1)$ (9.1.67)  
Equation (9.5.65), in the limit M->0, reduces to  
$$R_{c} = \frac{6(1+S^{-1})}{5C^{*}}$$
(9.1.68)

From (9.1.68), it is evident that  $R_c$  depends on segregation ratio parameter and the Sekerka number. When the density profile is quadratic, there is a drastic change in the value of  $R_c$ . Also in the  $Lt \not\in \to 0$ ,  $C^*$  becomes infinite so that  $R_c \to 0$ .

From the definitions of  $M^{-1}$  and  $\Gamma$ , both are inversely proportional to the solute concentration  $C_s$ . Therefore, increase in  $C_s$ , the value of wave number also increases as well as the cell structure will get contracted in case of a pure substance. Obviously,  $C_s = 0$  and a=0 and that corresponds to a planar interface. Suppose, we make an approximation that R=0, near M=1, then clearly M -1= O (a2) and from (9.1.63):

$$\sigma \sim (M-1)a^2 - a^4 \Gamma - k$$
 (Since M~1) (9.1.69)

To apply this approximation to (9.1.69), we obtain:

$$a_{c}^{2} = \frac{M-1}{M\Gamma\left(1+M^{\frac{1}{2}}\right)} \sim \left(\frac{M-1}{2\Gamma}\right)$$
(9.1.70)

As the asymptotic expansions considered in this study is valid only for a2 << 1 and hence from (9.1.70), we get:

$$\left(\frac{M-1}{2\Gamma}\right) <<1 \qquad \& \quad \& \quad \& <\frac{1}{4\Gamma} (M-1)^2 <<1$$
(9.1.71)

## IV. RESULTS AND DISCUSSIONS

The results are presented in the form of graphs for a wide range of parameters. The graphs corresponding to the linear theories are discussed in detail. The graphs reveal the points that are expressed below:

In Figures 9.1 to 9.3, the profiles of  $W_1$  are presented for different combinations of the parameters. While, Figure 9.1 predicts the variation of  $W_1$  w.r.t. A for k=0.001, M=1.025, S=10, R=0.44329 and  $\Gamma = 0.1$ . It is observed that,  $W_1$  decreases with z and is negative for all the combinations.



From Figures 9.4 to 9.6, it is clear that the effect of **B** is less, when compared to the effect of A on the  $C_1$  profiles. While in Figure 9.4, the influence of the parameter S is remarkable and  $C_1$  increases with S for a fixed value of z and other parameters. Also in Figure 9.7, the entire curves merge into a single curve. Figures 9.5 and 9.8 are similar but quantitatively differ from each other.



While in Figure 9.9, the effect of  $\Gamma$  is almost nil on the profile C1. In Figure 9.10, the graph of Rc vs S is plotted. In this graph, Rc is positive for  $\Gamma$ =0.1, while negative for  $\Gamma$ =0.5 and the effect of S is insignificant.





In Figure 9.11, the graph of  $\mathbf{a}_{c}^{2}$  vs  $\Gamma$  is linear whereas in Figure 9.12, the curves depict the effect of  $\Gamma$  on  $\mathbf{a}_{c}^{2}$  for a fixed value of M. Further, the effect of M is to increase the value of  $\mathbf{a}_{c}^{2}$  for fixed values of the parameters under consideration.







**Note:** In all the graphs,  $R = RC^*$  and  $Rc = Rc C^*$ .

#### **V. CONCLUSION**

Finally, it is concluded that these graphs are of immense use in predicting the influences of the different parameters either individually or cumulatively on the functions considered in a clear manner. This study predicts the nature of the solidification and profiles like velocity and concentration with small segregation coefficient

and for small wave number. Since, linear stability analysis has its own limitations; the nonlinear analysis would be recommended.

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