# A MATHEMATICAL MODEL FOR STABILITY OF THE FERRO-FLUID MELT IN A SPARSELY PACKED POROUS MEDIUM ROTATING ON A VERTICAL AXIS DURING THE SOLIDIFICATION OF A BINARY ALLOY

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# ABSTRACT

In this paper, the problem investigated on the effects of rotation and permeability of a sparsely packed fluid saturated porous medium using the Brinkman model. The study of the cumulative effect of rotation, magnetization, magnetic field concentration and permeability on the behaviour of the solidification problem is considered. The linear analysis and nonlinear analysis are carried out by using a modified power series technique.

Key Words - Binary Alloy, Stability Of Ferro-Fluid Melt, Rotation, Porous Medium

#### I. INTRODUCTION

The physical configuration constitutes the problem of solutal convection in a horizontal, sparsely packed incompressible and porous layer of ferromagnetic melt in the presence of vertical magnetic field as well as a uniform rotation about the vertical axis and buoyancy forces. From this a semi-infinite slab of crystal is being grown. In this study, the magnetization is a function of concentration. Thus, a concentration gradient is established across the fluid layer. Further, the modified permeability/porous parameter are the additional dimensionless parameter governing the problem. The qualitative and quantitative aspects of the problem are predicted by considering a proper choice of the parameters.

# **II. MATHEMATICAL FORMULATION**

In this study, the mathematical formulation has been constituted through extension of previous studies [3] and [4] as given in below equations:

The Conservation of momentum:

$$\left(\frac{\partial}{\partial t} + \mathbf{q}.\nabla\right)\mathbf{q} + 2\Omega \mathbf{k} \times \mathbf{q} = \nabla.(\mathbf{HB}) - \nabla \mathbf{p} + \alpha_{s} \mathbf{g} \mathbf{C} \mathbf{k} + v_{0} \frac{\partial \mathbf{q}}{\partial z} + v \nabla^{2} \mathbf{q} - \frac{v}{\boldsymbol{k}} \mathbf{q}$$
(5.1)

The Concentration equation:

$$\left[\rho C_{V,H} - \mu_{0}H \cdot \left(\frac{\partial M}{\partial C}\right)_{V,H}\right] \frac{dC}{dt} + \mu_{0}C \left(\frac{\partial M}{\partial C}\right)_{V,H} \cdot \frac{dH}{dt} + \rho_{c}(\mathbf{q} \cdot \nabla)C + \rho_{c}(\mathbf{q} \cdot \nabla)C_{0} = \rho_{c}v_{0}\frac{\partial C}{\partial z} + \rho_{c}d\nabla^{2}C \quad (5.2)$$

Along these equations, also consider the equations (3.1.3) to (3.1.10) from [3]. In equation (5.1), the viscosity is assumed to be isotropic and independent of the magnetic field where z-axis is vertical.

#### **III. BOUNDARY CONDITIONS**

All the boundary conditions i.e. (3.1.11) to (3.1.18) are considered and discussed in [3]. In addition to that the conditions on the vorticity are:

$$\zeta = 0 \text{ at } z = 0; \quad |\zeta| < \infty \text{ as } z \to \infty \tag{5.3}$$

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#### **3.1 Basic Solutions**

In this study, to get the same basic solutions are discussed in [3] and [6] and the vorticity will be  $\zeta = 0$ 

#### **IV. LINEAR STABILITY ANALYSIS**

In this section, the linear stability of the solutal convection in a ferro- porous melt under the influence of magnetization, rotation and magnetic field is being discussed in detail. While the structure of the pattern formation gives the growth of crystal formation. However, the influences of different governing parameters especially rotation on the velocity, concentration and magnetic field profiles are predictable only through nonlinear stability analysis, which is based on the results of the linear stability problem. Therefore, such an investigation is done here to throw light on those aspects of the present solidification problem [3] under rotation.

The perturbations are introduced to study the stability of the quiescent state is discussed in [3] and then (5.1), which can be written in the component form as follows:

$$\begin{pmatrix} \frac{\partial}{\partial t} + \mathbf{q} \cdot \nabla \end{pmatrix} \mathbf{u} - 2\mathbf{v} \,\Omega = -\frac{\partial}{\partial x} + \mu_0 (\mathbf{M}_0 + \mathbf{H}_0) \frac{\partial}{\partial z} + \mathbf{v}_0 \frac{\partial}{\partial z} + \mathbf{v} \nabla^2 \mathbf{u} - \frac{\mathbf{v}}{\mathbf{k}} \mathbf{u}$$

$$\begin{pmatrix} \frac{\partial}{\partial t} + \mathbf{q} \cdot \nabla \end{pmatrix} \mathbf{v} + 2\mathbf{u} \,\Omega = -\frac{\partial}{\partial y} + \mu_0 (\mathbf{M}_0 + \mathbf{H}_0) \frac{\partial}{\partial z} + \mathbf{v}_0 \frac{\partial}{\partial z} + \mathbf{v} \nabla^2 \mathbf{v} - \frac{\mathbf{v}}{\mathbf{k}} \mathbf{v}$$

$$\begin{pmatrix} \frac{\partial}{\partial t} + \mathbf{q} \cdot \nabla \end{pmatrix} \mathbf{w} = -\frac{\partial \mathbf{p}}{\partial z} + \mu_0 (\mathbf{M}_0 + \mathbf{H}_0) \frac{\partial}{\partial z} + \frac{\mathbf{v}}{\partial z} + \frac{\mathbf{v}}{\mathbf{k}} \mathbf{v} \nabla^2 \mathbf{v} - \frac{\mathbf{v}}{\mathbf{k}} \mathbf{v}$$

$$\begin{pmatrix} \frac{\partial}{\partial t} + \mathbf{q} \cdot \nabla \end{pmatrix} \mathbf{w} = -\frac{\partial \mathbf{p}}{\partial z} + \mu_0 (\mathbf{M}_0 + \mathbf{H}_0) \frac{\partial}{\partial z} + \frac{\mathbf{v}}{\partial z} + \frac{\mathbf{v}}{\mathbf{k}} \mathbf{v} \nabla^2 \mathbf{v} + \frac{\mathbf{v}}{\mathbf{k}} \mathbf{v}$$

$$+ \frac{\mathbf{u}}{\mathbf{k}} \frac{\mathbf{k}^2 \mathbf{C}}{(1 + \chi)} \frac{(1 - \xi) \mathbf{v}_0}{\mathbf{k}} \mathbf{e}^{-\mathbf{v}_0 \mathbf{z}} + \frac{\mathbf{v}}{\partial z} + \mathbf{v} \nabla^2 \mathbf{w} + \alpha_s \mathbf{g} \mathbf{C}' - \frac{\mathbf{v}}{\mathbf{k}} \mathbf{w}$$

$$(5.6)$$

Where, the primes denote the perturbed quantities. Differentiating (5.4), (5.5) and (5.6) w.r.t. x, y, z respectively and adding, we obtain:

$$-2\Omega D \zeta = -\frac{\partial}{\partial z} \nabla^{2} p + \mu_{0} (H_{0} + M_{0}) D^{2} (\nabla \cdot \mathbf{H}) - \mu * \left[ D^{2} H_{3}' - \frac{\mathbf{v}_{0}}{\mathbf{d}} D H_{3}' \right] + \mu * \left[ \frac{\mathbf{v}_{0}}{\mathbf{d}} D H_{3}' - \frac{\mathbf{v}_{0}^{2}}{\mathbf{d}^{2}} H_{3}' + \mathbf{K} D^{2} C - \frac{\mathbf{K} \mathbf{v}_{0}}{\mathbf{d}} D C - \frac{\mathbf{K} \mathbf{v}_{0}}{\mathbf{d}} D C + \frac{\mathbf{K} \mathbf{v}_{0}^{2}}{\mathbf{d}^{2}} C \right] + \alpha_{s} g D^{2} C', \text{ where } \mathbf{D} = \frac{\partial}{\partial z}$$
Now operate  $\nabla^{2}$  on (5.7) so

that: 
$$\left(\frac{\partial}{\partial t} + \mathbf{q} \cdot \nabla\right) \nabla^2 \mathbf{w} = -D\nabla^2 p + \mu_0 (H_0 + M_0) D\nabla^2 H_3' + \mu * \left[ -\nabla^2 H_3' - \frac{\nabla^2}{d^2} H_3' \right]$$

$$\mu * \left[ \frac{\mathbf{K} \mathbf{v}_{0}^{2}}{\mathsf{d}^{2}} C' + \mathbf{K} \nabla^{2} C' \right] + \mathbf{v}_{0} \nabla^{2} w + \mathbf{v} \nabla^{4} w + \alpha_{s} g \nabla^{2} C' - \frac{\mathbf{v}}{\mathcal{K}} \nabla^{2} w$$
(5.7a)

Subtracting (5.7) from the resulting equation (5.7a), to obtain:

$$\left(\frac{\partial}{\partial t} + \mathbf{q} \cdot \nabla\right) \nabla^{2} \mathbf{w} = \mu^{*} \left[ -D\Delta_{2} \varphi + \frac{\mathbf{K}}{(1+\chi)} \Delta_{2} C - \frac{2\nu_{0}}{d} D^{2} \varphi + \frac{2 \mathbf{K} \nu_{0}}{d(1+\chi)} DC \right] + \nu_{0} D \nabla^{2} \mathbf{w} + \nu \nabla^{4} \mathbf{w} + \alpha_{s} g \Delta_{2} C - 2 \Omega D \zeta - \frac{\nu}{\hat{k}_{s}} \nabla^{2} w$$

$$(5.8)$$

Now, the elimination of pressure from (5.4) and (5.5) results in the following vorticity equation:

$$\left(\frac{\partial}{\partial t} + \mathbf{q} \cdot \nabla - \mathbf{v}_0 D - \mathbf{v} \nabla^2\right) \zeta = 2 \, \Omega D_W - \frac{\mathbf{v}}{\mathbf{k}} \zeta \tag{5.8a}$$

Where,

$$\zeta = \frac{\partial \mathbf{v}}{\partial \mathbf{x}} - \frac{\partial \mathbf{u}}{\partial \mathbf{y}} \text{ is the } \mathbf{z} \text{ - component of vorticity,}$$
(5.8b)

$$\mu^* = \frac{\mu_0 \mathbf{K} (1 - \ell_c) v_0 C_{\infty}}{\ell_c d} e^{-\frac{v_0 C_{\infty}}{\ell_c d}} \quad \text{and} \quad \mathsf{D} = \frac{\mathsf{d}}{\mathsf{d} \mathsf{z}}, \ \mathbf{H} = \nabla \varphi, \tag{5.9}$$

 $\Delta_2$  is the 2-dimensional Laplacian operator and the primes are dropped for the sake of convenience. Also, the simplification of (5.3) is discussed in [3].

Now, all the three simplified governing equations converted into dimensionless form by using the scales are discussed in [3] and then, the resulting dimensionless set of linearized equations (in the limit of infinite Schmidt

number Sc = 
$$\frac{v}{d}$$
) is as follows:  

$$\nabla^{4} \mathbf{w} \cdot \mathbf{M}_{1} \operatorname{Re}^{-Z} (\Delta_{2} + 2D) \operatorname{H}_{3} + \operatorname{M}_{1} \operatorname{Re}^{-Z} (2D + \Delta_{2}) \operatorname{C} + \operatorname{R} \Delta_{2} \operatorname{C} \cdot \operatorname{N}^{\frac{1}{2}} D\zeta - PL \nabla^{2} w = 0 \qquad (5.10)$$

$$\left( D^{2} + \operatorname{M}_{3} \Delta_{2} \right) \operatorname{H}_{3} - D^{2} \operatorname{C} = 0 \qquad (5.11)$$

$$\left( \nabla^{2} + D - \frac{\partial}{\partial t} \right) \operatorname{C} + \left( \operatorname{M}_{2} + \operatorname{M}_{2}^{*} \operatorname{e}^{-Z} \right) \frac{\partial \operatorname{H}_{3}}{\partial t} + \left[ (1 - \operatorname{M}_{2}) - \operatorname{M}_{2}^{*} \operatorname{e}^{-Z} \right] \operatorname{e}^{-Z} w = 0 \qquad (5.12)$$

$$N^{\frac{1}{2}} Dw + \nabla^{2} \zeta - PL \zeta = 0 \qquad (5.12a)$$

Where,  $M_1$ ,  $M_2$ ,  $M_3$  and  $M_2^*$  are defined in [3]. Along these, the other dimensionless parameters are defined as follows:

$$R = \frac{(1 - k) \alpha_{s} C_{\infty} d^{2}}{v v_{0}^{3} k}$$
: Solidification Rayleigh number,  $N = \frac{4\Omega^{2} d^{4}}{v^{2} v_{0}^{4}}$ : Solidification Taylor number,

$$PL = \frac{1}{P_{\ell}} = \frac{d^2}{v_0^2 \xi^*}$$
: Modified permeability parameter

The linear stability analysis is carried out by studying the stability of the basic state by the method of infinitesimal perturbation. The approach is similar to that of [3] and [6] and the system was analyzed by using normal modes in the x, y and t variables in the limit of critical wave number approaching zero as  $k\rightarrow 0$ . Thus, we set the solution in the following form:

$$(w, C, H_{3}, \zeta) = [F(z), G(z), J(z), F^{*}(z)] e^{(\sigma t + i\hat{k} \cdot r)}$$
(5.13)

Where,  $\mathbf{r} = \hat{\mathbf{i}}\mathbf{x} + \hat{\mathbf{j}}\mathbf{y}$ ;  $\alpha = \sqrt{\left(k_x^2 + k_y^2\right)}$ : the horizontal wave number  $\sigma$ : The growth rate of the disturbance  $\nabla_1^2 \mathbf{f} = \Delta_2 \mathbf{f} = -\alpha^2 \mathbf{f}$ ;  $\nabla^2 f = \left(D^2 - \alpha^2\right) \cdot f$ ;  $\mathbf{f} = \mathbf{f}(\mathbf{x}, \mathbf{y})$ (5.14)

The substitution of (5.14) with (5.10) to (5.12a) results in the following eigenvalue problem for which  $\sigma$  is the eigenvalue:

$$\left( D^{2} - \alpha^{2} \right)^{2} F - M_{1} Re^{-Z} \left( 2D - \alpha^{2} \right) J - N^{\frac{1}{2}} DF^{*} + R \left\{ M_{1} e^{-Z} \left( 2D - \alpha^{2} \right) - \alpha^{2} \right\} G - PL \left( D^{2} - \alpha^{2} \right) F = 0$$

$$N^{\frac{1}{2}} DF + \left( D^{2} - \alpha^{2} \right) F^{*} = PIF^{*} = 0$$

$$(5.15)$$

$$N^{\frac{1}{2}}DF + (D^{2} - \alpha^{2}) \cdot F^{*} - PLF^{*} = 0$$
(5.15a)
$$(D^{2} - M_{3}\alpha^{2})J - D^{2}G = 0$$
(5.16)

$$\left( D^{2} + D - \alpha^{2} - \sigma \right) G + \left( M_{2} + M_{2}^{*} e^{-z} \right) \sigma J + \left\{ (1 - M_{2}) - M_{2}^{*} e^{-z} \right\} e^{-z} F = 0$$

$$(5.17)$$

With the following boundary conditions:

$$F^* = F = DF = J = (D+1) G = 0 \text{ at } z = 0$$

$$|F^*| < \infty, |F| < \infty, |J| < \infty, G = 0 \text{ as } z \rightarrow \infty$$
(5.18)
(5.19)

In order to obtain the solutions are corresponding to different orders, a power series expansion for the dependent variables including R and  $\sigma$  is assumed as follows:

| [F] | [F <sub>0</sub> ]         | [F <sub>1</sub> ]                  |
|-----|---------------------------|------------------------------------|
| G   | G <sub>0</sub>            | G 1                                |
| J   | J <sub>0</sub>            | $  J_1  $                          |
| F   | =   .<br>  F <sub>0</sub> | $  + \alpha   + \alpha   + \cdots$ |
| R   | R 0                       | R <sub>1</sub>                     |
| σ   | σ,                        | σ <sub>1</sub>                     |

By substituting (5.20) with (5.15) to (5.20) yields the following zeroth– order system of differential equations:

$$D^{2}(D^{2} - PL)F_{0} - 2M_{1}R_{0}e^{-Z}(DJ_{0} - DG_{0}) - N^{\frac{1}{2}}DF_{0}^{*} = 0$$

$$N^{\frac{1}{2}}DF_{0} + (D^{2} - PL)F_{0}^{*} = 0$$

$$D^{2}G_{0} - D^{2}J_{0} = 0$$

$$(D^{2} + D - \sigma_{0})G_{0} + (M_{2} + M_{2}^{*}e^{-Z})\sigma_{0}J_{0} + \{(1 - M_{2}) - M_{2}^{*}e^{-Z}\}e^{-Z}F_{0} = 0$$
(5.21)
The solution of (5.21) is given by:

 $F_0 = 0, F_* = 0, G_0 = g_0 e^{-z}, J_0 = g_0 (e^{-z} - 1), \text{ where } g_0 \text{ is a constant of integration.}$  (5.22) The next higher-order system of differential equations, i.e.  $(o(\alpha^2))$  are:

$$D^{2}(D^{2} - PL)F_{1} - 2M_{1}R_{0}e^{-z}(DJ_{1} - DG_{1}) - N^{\frac{1}{2}}DF_{1}^{*} = R_{0}g_{0}(1 + M_{1})e^{-z}$$

$$N^{\frac{1}{2}}DF_{1} + (D^{2} - PL)F_{1}^{*} = 0$$

$$D^{2}J_{1} - M_{3}J_{0} - D^{2}G_{1} = 0$$

$$(D^{2} + D)G_{1} + ((1 - M_{2}) - M_{2}^{*}e^{-z})e^{-z}F_{1} = \{g_{0} + \sigma_{1}g_{0}(1 - M_{2} + M_{2}^{*})\}e^{-z} - \sigma_{1}g_{0}M_{2}e^{-2z} + \sigma_{1}g_{0}M_{2}$$
(5.23)

The solutions of the system (5.23) with the boundary conditions (5.18) and (5.19) are given by:

$$\begin{aligned} F_{1} &= f_{1}e^{-Z} + f_{2}ze^{-Z} + f_{3}e^{-2Z} + f_{4} \\ F_{1}^{*} &= f_{1}^{*}e^{-Z} + f_{2}^{*}ze^{-Z} + f_{3}^{*}e^{-2Z} + f_{4}^{*}e^{-Z\sqrt{PL}} \\ G_{1} &= g_{1}ze^{-Z} + g_{2}e^{-2Z} + g_{3}ze^{-2Z} + g_{4}e^{-3Z} + g_{5}ze^{-3Z} + g_{6}e^{-4Z} \\ J_{1} &= j_{1}e^{-Z} + j_{2}ze^{-Z} + j_{3}e^{-2Z} + j_{4}ze^{-2Z} + j_{5}e^{-3Z} + j_{6}ze^{-3Z} + j_{7}e^{-4Z} + j_{8} \end{aligned}$$
(5.24)  
Where,  $f_{1} &= -\frac{2M_{1}M_{3}R_{0}g_{0}}{\left\{(1 - PL)^{2} + N\right\}} + \frac{(4 - PL)M_{1}M_{3}R_{0}g_{0}}{\left\{(4 - PL)^{2} + N\right\}}, \quad f_{2} &= -\frac{2M_{1}M_{3}R_{0}g_{0}(1 - PL)}{\left\{(1 - PL)^{2} + N\right\}}, \\ f_{3} &= -\frac{M_{1}M_{3}R_{0}g_{0}(4 - PL)}{2\left\{(4 - PL)^{2} + N\right\}}, \quad f_{4} &= \frac{2M_{1}M_{3}R_{0}g_{0}}{\left\{(1 - PL)^{2} + N\right\}} + f_{3}, \quad f_{1}^{*} &= N^{\frac{1}{2}}\left[f_{1} + \frac{f_{2}}{(1 - PL)}\left\{\frac{2}{(1 - PL)} - 1\right\}\right], \\ f_{2}^{*} &= \frac{N^{\frac{1}{2}}f_{2}}{(1 - PL)}, \quad f_{3}^{*} &= \frac{2N^{\frac{1}{2}}f_{3}}{(4 - PL)}, \quad f_{4}^{*} &= -(f_{1}^{*} + f_{3}^{*}), \quad a_{1} &= g_{0} + \sigma_{1}g_{0}(1 + M_{2}^{*} - M_{2}), \quad a_{2} &= \sigma_{1}g_{0}M_{2}^{*}, \quad a_{3} &= \sigma_{1}g_{0}M_{2}^{*}, \end{aligned}$ 

(5.20)

$$a_{4} = a_{1} + f_{4}(M_{2} - 1), a_{5} = \left\{-a_{2} + f_{1}(M_{2} - 1) + M_{2}^{*}f_{4}\right\}, a_{6} = f_{2}(M_{2} - 1), a_{7} = f_{3}(M_{2} - 1) + M_{2}^{*}f_{1}, a_{8} = M_{2}^{*}f_{2}, a_{9} = M_{2}^{*}f_{3}, g_{1} = -a_{4}, g_{2} = \frac{1}{2}a_{5} + \frac{3}{4}a_{6}, g_{3} = \frac{1}{2}a_{6}, g_{4} = \frac{1}{6}a_{7} + \frac{5}{36}a_{8}, g_{5} = \frac{1}{6}a_{8}, g_{6} = \frac{1}{12}a_{9}, j_{1} = M_{3}g_{0}, j_{2} = g_{1}, j_{3} = g_{2}, j_{4} = g_{3}, j_{5} = g_{4}, j_{6} = g_{5}, j_{7} = g_{6}, j_{8} = -(j_{1} + j_{3} + j_{5} + j_{7}).$$

Further, the boundary condition for  $G_1$  i.e.,  $(D + 1) G_1 = 0$  at z = 0 (5.25)

Yields the following expression for the growth rate  $\sigma_1$ :

$$\sigma_{1} = \underbrace{\left[\sum_{i=1}^{3} S_{i} - 1\right]}_{S_{4}}$$
(5.26)  
Where,  $S_{1} = M_{1}M_{3}R_{0} \left[\frac{\left\{1 - \frac{(1 - PL)}{2}\right\}}{\left\{(1 - PL)^{2} + N\right\}} - \frac{(4 - PL)}{6\left\{(4 - PL)^{2} + N\right\}}\right], \qquad S_{4} = \left(1 - M_{2} + \frac{M_{1}^{2}}{2}\right)$   
 $S_{2} = \frac{M_{1}M_{3}M_{2}R_{0}}{\left\{(1 - PL)^{2} + N\right\}} \left[\frac{(6 - 1)/6}{3} \left\{1 - \frac{2}{3}(1 - PL)\right\} - \left\{1 - \frac{(1 - PL)}{2}\right\}\right], \qquad S_{3} = -\frac{M_{1}M_{3}M_{2}R_{0}(4 - PL)}{6\left\{(4 - PL)^{2} + N\right\}} \left[\frac{(6 - 1)/6}{4}\right] - 1\right]$   
In the limit  $M_{2} \to 0$ , (5.26) reduces to:  
 $\sigma_{1} = M_{1}M_{3}R_{0} \left[\frac{\left\{1 - \frac{(1 - PL)}{2}\right\}}{\left\{(1 - PL)^{2} + N\right\}} - \frac{(4 - PL)}{6\left\{(4 - PL)^{2} + N\right\}}\right] - 1$  (5.27)  
In the absence of porous and rotation (5.27) reduces to [3] of (3.3.32).  
The condition that  $\sigma_{1}$  is real and positive gives:  
 $R_{0} > \frac{1}{M_{1}M_{3}(S_{5} + S_{6}^{2} + S_{7})}$ (5.28)  
Where,  $S_{6} = \frac{M_{1}M_{3}M_{2}}{\left\{(1 - M_{2})^{2} - M_{1}^{2}\right\}} \left[\frac{(6 - 1)/6}{2}\left(1 - PL\right)\left\{-\left\{1 - \frac{(1 - PL)}{2}\right\}\right\}\right],$ 

$$S_{5} = M_{1}M_{3}\left[\frac{\left\{1 - \frac{PL}{2}\right\}}{\left\{\left(1 - PL\right)^{2} + N\right\}} - \frac{3}{6\left\{\left(4 - PL\right)}\right\}}{6\left\{\left(4 - PL\right)^{2} + N\right\}}\right], S_{7} = -\frac{M_{1}M_{3}M_{2}(4 - PL)}{6\left\{\left(4 - PL\right)^{2} + N\right\}}\left[\left(\frac{\left(\frac{k}{2} - 1\right)}{\frac{k}{2}}\right) - 1\right]\right]$$
And
$$R_{0} = \frac{1}{M_{1}M_{3}R_{0}\left[\frac{\left\{1 - \frac{(1 - PL)}{2}\right\}}{\left\{\left(1 - PL\right)^{2} + N\right\}} - \frac{(4 - PL)}{6\left\{\left(4 - PL\right)^{2} + N\right\}}\right]}{6\left\{\left(4 - PL\right)^{2} + N\right\}}\right]}$$
(5.29)

In the absence of porocity and rotation (5.29) reduces to [3] of (3.3.34).

Thus, for marginal stability: 
$$R_0 = \frac{1}{M_1 M_3 (S_5 + S_6 + S_7)}$$
 (5.30)

In the next higher approximation, the corresponding differential equations are given by:

$$D^{2} (D^{2} - PL)F_{2} - 2 M_{1} R_{0} e^{-Z} (D J_{2} - D G_{2}) - N^{\frac{1}{2}} DF_{2}^{*} = (2 D^{2} - PL)F + 2M_{1}R_{1}e^{-Z} (D J_{1} - D G_{1})_{1} + 2 M_{1} R_{2}e^{-Z} (D J_{0} - D G_{0}) - M_{1}R_{0}e^{-Z} (J_{1} - G_{1}) - M_{1}R_{1}e^{-Z} (J_{0} - G_{0}) + R_{1}G_{0} + R_{0}G_{1}$$
(5.31)

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$$N^{\frac{1}{2}} DF_{2} + (D^{2} - PL)F_{2}^{*} - F_{1}^{*} = 0$$
(5.31a)
$$D^{2} J_{2} - M_{3}J_{1} - D^{2} G_{2} = 0$$
(5.32)
$$(D^{2} + D)G_{2} + \{(1 - M_{2}) - M_{2}^{*}e^{-Z}\}e^{-Z} F_{2} = (1 + \sigma_{1})G_{1} + \sigma_{2} g_{0} e^{-Z}$$

$$- (M_{2} + M_{2}^{*}e^{-Z})\{\sigma_{2}(g_{0}e^{-Z} - g_{0}) + \sigma_{1}j_{1}\}$$
(5.33)

The above system of inhomogeneous differential equations is quite complicated along with the complex boundary conditions. While the solution procedure is quite tedious, only the final solutions are presented by avoiding the details, which are as follows:

$$\begin{split} & F_{2} = f_{4} e^{-2} + f_{6} z^{-2} + f_{6} z^{-2} z^{-2} + f_{4} z^{-2} z^{-2} + f_{4} e^{-32} + f_{10} z^{-32} + f_{10} z^{-32} + f_{10} z^{-34} + f_{1$$

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Where, 
$$\mathbf{a}_{19} = \sigma_2 \sigma_0 \left(\mathbf{i} + W_2^2 - M_2\right) - \sigma_1 \left(W_2^2 \mathbf{i}_8 + W_2 \mathbf{i}_1\right) - \left(\mathbf{1} - W_2\right) \mathbf{f}_{14}, \mathbf{a}_{20} = (\mathbf{1} + \sigma_1) \mathbf{g}_1 - M_2 \sigma_1 \mathbf{j}_2, \mathbf{a}_{21} = (\mathbf{1} + \sigma_1) \mathbf{g}_2 - M_2^2 \sigma_2 \mathbf{g}_0 - \sigma_1 \left(W_2 \mathbf{j}_1 + M_2^2 \mathbf{j}_1\right) - (\mathbf{1} - M_2) \mathbf{f}_5 + M_2^2 \mathbf{j}_{14}, \mathbf{a}_{26} = -M_2^2 \sigma_1 \mathbf{j}_6 - (\mathbf{1} - M_2) \mathbf{j}_{10} + M_2^2 \mathbf{f}_8$$
  
 $\mathbf{a}_{22} = (\mathbf{1} + \sigma_1) \mathbf{g}_3 - M_1^2 \sigma_1 \mathbf{j}_2 - \sigma_1 \mathbf{M}_2 \mathbf{j}_4 - (\mathbf{1} - M_2) \mathbf{f}_6, \mathbf{a}_{32} = (\mathbf{1} + \sigma_1) \mathbf{g}_4 - M_2^2 \sigma_1 \mathbf{j}_5 - (\mathbf{1} - M_2) \mathbf{j}_{10} + M_2^2 \mathbf{f}_5, \mathbf{a}_{36} = (\mathbf{1} - \mathbf{M}_2) \mathbf{f}_{11} + M_2^2 \mathbf{f}_{10}, \mathbf{a}_{30} = M_2^2 \mathbf{f}_{12}, \mathbf{a}_{36} = (\mathbf{1} - M_2) \mathbf{f}_{11} + M_2^2 \mathbf{f}_{10}, \mathbf{a}_{30} = M_2^2 \mathbf{f}_{12}, \mathbf{a}_{36} = (\mathbf{1} - M_2) \mathbf{f}_{11} + M_2^2 \mathbf{f}_{10}, \mathbf{a}_{30} = M_2^2 \mathbf{f}_{12}, \mathbf{a}_{39} = -(\mathbf{1} - M_2) \mathbf{f}_{11} + M_2^2 \mathbf{f}_{11}, \mathbf{a}_{31} = M_2^2 \mathbf{f}_{13}, \mathbf{b}_{19} = \sigma_1 \left(W_2 \mathbf{j}_1 \mathbf{j}_1 + W_2^2 \mathbf{j}_8\right) + (\mathbf{1} - M_2) \mathbf{f}_{11} + M_2^2 \mathbf{f}_{10}, \mathbf{a}_{30} = M_2^2 \mathbf{f}_{12}, \mathbf{a}_{39} = -(\mathbf{1} - M_2) \mathbf{f}_{11} + M_2^2 \mathbf{f}_{10}, \mathbf{a}_{30} = M_2^2 \mathbf{f}_{12}, \mathbf{a}_{39} = -(\mathbf{1} - M_2) \mathbf{f}_{11} + M_2^2 \mathbf{f}_{10} + (\mathbf{1} - M_2) \mathbf{f}_{2} - (\mathbf{1} + \sigma_1) \mathbf{g}_{2} - M_2^2 \mathbf{f}_{14}\right), \mathbf{g}_{7} = -(\mathbf{a}_{19} + \mathbf{a}_{30}), \mathbf{g}_{8} = -\frac{1}{2} \mathbf{a}_{30}, \mathbf{g}_{10} = \frac{\mathbf{a}_{32}}{\mathbf{2}}, \mathbf{g}_{9} = \frac{\mathbf{a}_{31}}{\mathbf{a}} + \frac{\mathbf{a}_{32}}{\mathbf{a}} + \frac{\mathbf{a}_{32}}{\mathbf{a}}, \mathbf{g}_{11} = \frac{\mathbf{a}_{33}}{\mathbf{a}}, \mathbf{g}_{12} = \frac{\mathbf{a}_{34}}{\mathbf{a}}, \mathbf{g}_{12} = \frac{\mathbf{a}_{34}}{\mathbf{a}}, \mathbf{g}_{12} = \frac{\mathbf{a}_{34}}{\mathbf{a}}, \mathbf{g}_{12} = \frac{\mathbf{a}_{34}}{\mathbf{a}}, \mathbf{g}_{12} = \mathbf{a}_{36}, \mathbf{g}_{16} = \frac{\mathbf{a}_{32}}{\mathbf{a}}, \mathbf{g}_{16} = \frac{\mathbf{a}_{32}}{\mathbf{a}}, \mathbf{g}_{16} = \frac{\mathbf{a}_{33}}{\mathbf{a}}, \mathbf{g}_{16} = \frac{\mathbf{a}_{34}}{\mathbf{a}}, \mathbf{g}_{16} = \frac{\mathbf{a}_{34}}{\mathbf{a}}, \mathbf{g}_{16} = \frac{\mathbf{a}_{34}}{\mathbf{a}}, \mathbf{g}_{16} = \frac{\mathbf{a}_{36}}{\mathbf{a}}, \mathbf{g}_{16} = \mathbf{a}_{36} + \mathbf{a}_{36} = \mathbf{a}_{36} + \mathbf{a}$ 

The results are presented through a number of graphs.

# V. NONLINEAR ANALYSIS

The nonlinear analysis of any physical problem is capable of predicting several qualitative as well as the quantitative aspects of the problem under consideration. Therefore, in this section, the weakly nonlinear behaviour of the system consisting of the ferromagnetic melt with solidification front at the interface subjected to uniform rotation and magnetic field are investigated. Now, express the variables q, B and H in terms of the poloidal components as:

$$(q, B, H, \zeta) = \delta(\varphi, \psi, E, \varphi^*)$$
(5.39)

With,  $\delta = \nabla \times \nabla \times \mathbf{k}$  (5.40) Substituting these polodial components into the system (3.1.3) to (3.1.8) in [3] and also, in the system (5.1) to

(5.2). Then, to get the following nonlinear system of equations after some mathematical simplification:

$$\Delta_{2}\left[\left(D^{2}+\Delta_{2}\right)\left(D^{2}+\Delta_{2}-PL\right)\varphi-RC\right]+N^{\frac{1}{2}}\Delta_{2}D\varphi^{*}=-M_{1}R\left\{\delta\left(\delta\psi\cdot\nabla\delta E\right)\cdot\overset{\wedge}{\mathbf{k}}\right\}$$
(5.41)

$$\Delta_{2}\left[N^{\frac{1}{2}}D\phi + \left(\Delta_{2} + D^{2} - PL\right)\phi^{*}\right] = 0$$
(5.41a)

$$\Delta_2 \left( D^2 + M_3 \Delta_2 \right) E + D^2 C = 0 \tag{5.42}$$

$$\left(\nabla^{2} + D - \frac{\partial}{\partial t}\right) \mathbf{C} - \Delta_{2} \left\{ \left(1 - M_{2}\right) - M_{2} \mathbf{e}^{-z} \right\} \mathbf{e}^{-z} \phi - \Delta_{2} \left(M_{2} + M_{2}^{*} \mathbf{e}^{-z}\right) \frac{\partial E}{\partial t} = \mathbf{\delta} \phi \cdot \nabla C$$
(5.43)

The analysis is carried out for small k also. The governing system of nonlinear differential equations in terms of the rescaled variables (rescaled variables are Ref [4]) takes the form (after dropping the primes):

$$\Delta_{2}\left\{\left(\epsilon \Delta_{2} + D^{2}\right)\left(\epsilon \Delta_{2} + D^{2} - PL\right)\phi - \epsilon R_{0}\left(1 + \epsilon \gamma\right)C + N^{\frac{1}{2}}D\phi^{*}\right\} = -M_{1} \epsilon R_{0}\left(1 + \epsilon \gamma\right)\left\{\delta\left(\delta\psi\cdot\nabla\delta E\right)\cdot\hat{\mathbf{k}}\right\}$$
(5.44)  
$$\Delta_{2}\left[N^{\frac{1}{2}}D\phi + \left(\epsilon \Delta_{2} + D^{2} - PL\right)\phi^{*}\right] = 0$$
(5.44a)  
$$\Delta_{2}\left(D^{2} + \epsilon M_{3}\Delta_{2}\right)E + D^{2}C = 0$$
(5.45)  
$$\left(D^{2} + D + \epsilon\Delta_{2} - \epsilon^{2}\frac{\partial}{\partial t}\right)C - \Delta_{2}\left\{\left(1 - M_{2}\right) - M_{2}^{*}e^{-z}\right\}e^{-z}\phi - \epsilon^{2}\Delta_{2}\left(M_{2} + M_{2}^{*}e^{-z}\right)\frac{\partial E}{\partial t} = \delta\phi\cdot\nabla C$$
(5.46)

Together with:

$$\varphi^* = \varphi = D \varphi = E = (D + 1 - \varepsilon^2 k_1)C = 0 \qquad \text{at} \qquad Z = 0$$
$$\left|\varphi^*\right| < \infty, \left|\varphi\right| < \infty, \quad |\mathsf{E}| < \infty, \quad \mathsf{C} = 0 \qquad \text{as} \qquad Z \to \infty$$

The solution of the nonlinear system (5.41) to (5.46) subject to the boundary conditions (5.47) in terms of a power series inc, of the form:

$$\begin{bmatrix} \varphi \\ \mathsf{E} \end{bmatrix} = \sum_{m \neq 1} \varepsilon^{m} \begin{bmatrix} \varphi_{m} \\ \mathsf{E}_{m} \end{bmatrix}$$

# (5.48)

Substituting (5.48) into (5.44) to (5.47) and the corresponding differential equations of O ( $\epsilon$ ) are as follows:  $\Delta_{\alpha} D^{2} (D^{2} - PL_{\alpha} + N^{\frac{1}{2}} \Delta_{\alpha} D_{\alpha}) = 0$ 

$$\Delta_{2} \begin{bmatrix} N^{\frac{1}{2}} D \varphi_{1} + (D^{2} - PL) \varphi_{1}^{*} \end{bmatrix} = 0$$

$$\Delta_{2} D^{2} E_{1} + D^{2} C_{1} = 0$$

$$(D^{2} + D) C_{1} - \Delta_{2} \{ (1 - M_{2}) - M_{2}^{*} e^{-z} \} e^{-z} \varphi_{1} = 0$$
Together with:

 $\varphi_1 = \varphi_1^* = D \varphi_1 = E_1 = (D+1)C_1 = 0 \text{ at } z = 0$   $\left| \varphi_1^* \right| < \infty, \quad \left| E_1 \right| < \infty, \quad C_1 = 0 \text{ as } z \to \infty$  (5.50)On solving the above system to obtain:

 $\varphi_1^* = 0; \quad \varphi_1 = 0; \quad C_1 = Ae^{-z}, \quad E_1 = \frac{A}{\Delta_2} (1 - e^{-z})$ (5.51)

Where, A = A(x, y, t) is an amplitude function.

In order to obtain more accurate results, the higher order solutions are computed i.e.  $(o(\epsilon^2))$ :

$$D^{2}(D^{2} - PL)\varphi_{2} + N^{\frac{1}{2}}D\varphi_{2}^{*} = R_{0}A e^{-z}$$
(5.53)

$$N^{\frac{1}{2}} D \varphi_2 + \left( D^2 - PL \right) \varphi_2^* = 0$$
(5.54)

$$\Delta_{2} D^{2} E_{2} + D^{2} C_{2} = M_{3} A \Delta_{2} e^{-z} - M_{3} \Delta_{2} A = M_{3} \Delta_{2} A \left(e^{-z} - 1\right)$$
(5.55)

(5.52)

(5.47)

$$\begin{pmatrix} D^{2} + D \end{pmatrix} C_{2} - \Delta_{2} \left\{ (1 - M_{2}) - M_{2}^{2} e^{-Z} \right\} e^{-Z} \varphi_{2} = -\Delta_{2} A e^{-Z}$$
(5.56)  
By using the corresponding boundary conditions, the solution of the above system are given by:  

$$\varphi_{2}^{*} = \frac{F_{1}}{\varpi}$$
(5.57)  
Where,  $D = -\left(\frac{M_{1}M_{3}g_{0}}{A}\right) \left[ \frac{(1 - PL)}{b_{10}} - 2 + \frac{(4 - PL)b_{10}}{b_{11}} - 4 PL \right]$   
Equation (5.58) can be written as:  

$$\varphi_{2}^{*} = q_{1}^{*}e^{-z} + q_{2}^{*}z^{-2z} + q_{3}^{*}e^{-2z} + q_{4}^{*}$$
(5.59)  
Where,  $q_{1}^{*} = \frac{f_{1}}{\varpi}, q_{2}^{*} = \frac{f_{2}}{\varpi}, q_{3}^{*} = \frac{f_{3}}{\varpi}, q_{4}^{*} = \frac{f_{4}}{\varpi}$   
Correspondingly, we can write  

$$\varphi_{2} = q_{1}e^{-z} + q_{2}ze^{-z} + q_{3}e^{-2z} + q_{4}z + q_{5}$$
(5.60)  
Where,  $q_{1} = N^{-\frac{1}{2}} \left\{ (1 - PL) q_{1}^{*} - (1 + PL) q_{2}^{*} \right\}, \quad q_{2} = N^{-\frac{1}{2}} (1 - PL) q_{2}^{*}, \quad q_{3} = 2N^{-\frac{1}{2}} \left\{ 2 - \frac{PL}{2} \right\} q_{3}^{*},$   

$$q_{4} = N^{-\frac{1}{2}} PLq_{4}^{*}, \quad q_{5} = -(q_{1} + q_{3})$$
(5.61)  

$$E_{2} = \frac{A}{g_{0}} J_{1}$$
(5.62)  
Where, the expressions for E<sub>1</sub>. G<sub>1</sub> and J<sub>1</sub> are given by (5.24). The evolution equation can be obtained

Where, the expressions for  $F_1$ ,  $G_1$  and  $J_1$  are given by (5.24). The evolution equation can be obtained by integrating (5.46), in the order of  $\varepsilon^3$ , with respect to z from z = 0 to  $\infty$  and using (5.57) and the solutions corresponding to O ( $\varepsilon^3$ ). As the equations are highly complicated, the expressions are not presented here for the determination of the amplitude A.

# VI. RESULTS AND DISCUSSIONS

The results are presented in the form of graphs for a wide range of parameters. The graphs corresponding to linear theories as well as nonlinear theories are discussed in detail. The graphs reveal the following points: In figure 5.1, the graph of  $R_0$  vs.  $M_3$  are presented for different values of N. It was found that  $R_0$  decreases tremendously with  $M_3$  for all values of N. Also, the figures 5.2 and 5.3 present a comparison of the profiles for  $F_1$ ,  $G_1$ ,  $I_1$  and  $H_1$  as well as a comparison of the profiles  $F_2$ ,  $G_2$ ,  $J_2$  and  $H_2$  for k=0.001,  $g_0 = 0.5$ ,  $M_3 = 10$ ,  $N = 10^3$  and PL =  $10^2$ .



In figure 5.4, the curves for  $R_0$ ,  $\phi_2$  and  $\phi_2^{'}$  are presented for A = 8.8857866. All the three curves gradually decrease with z and the values are high in the range  $5 \le z \le 10$ . For any specific value of z, it was found

that  $F_2 < R_0 < F_2^*$ . Also in figure 5.5, the effect of increase in PL is to reduce the value of C<sub>2</sub>) for fixed values of the other parameters. While, the figure 5.6 represents the graph of R<sub>2</sub> vs. g<sub>0</sub> is presented for fixed values of z, PL and A. As per the physical situation, R<sub>0</sub> has very significant value for rotation rates N = 10, 10<sup>2</sup>, 10<sup>3</sup> and for large values of g<sub>0</sub>. The interesting feature observed is that the Ferro-convective instability is **effective** only in the **large rotation rates** (N > 10<sup>3</sup>) irrespective of the values of g<sub>0</sub>



The graphs of  $E_2$  vs. z are presented in the figures 5.7 and 5.8 in order to study the variation of the rotation and morphological parameters of  $E_2$ . It was observed that increase in N causes an enhancement in the values of  $E_2$ and increase in  $M_3$  causes reduction in the values of  $E_2$ .

![](_page_9_Figure_4.jpeg)

#### VII. CONCLUSION

Finally, it is concluded that, these graphs are of immense use in predicting the influences of the different parameters either individually or cumulatively on the functions considered in a clear manner. Further, this study predicts the nature of the solidification in a sparsely packed porous medium rotating on a vertical axis.

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